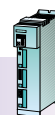


SIMOVERT MASTERDRIVES Motion Control

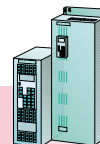
Engineering information

Electronics options

Compact PLUS units



Compact and chassis units



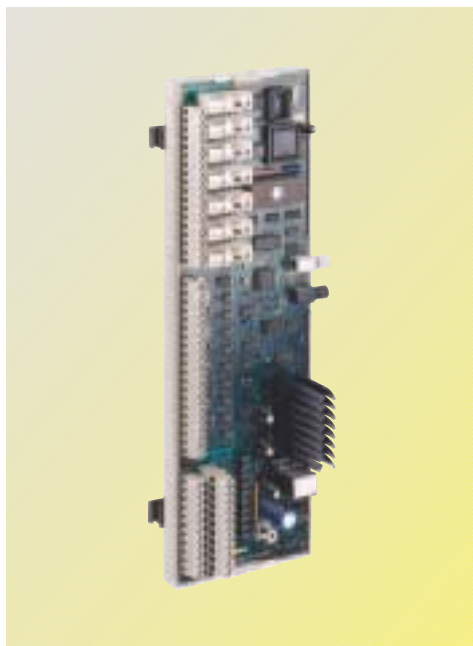
SCI1 and SCI2 interface boards

A serial I/O system using fiber-optic cables can be established with the SCI1 and SCI2 (Serial Communication Interface 1 or 2) interface boards and the SCB1 interface board. This allows the number of binary and analog inputs and outputs to be considerably expanded. In addition, the fiber-optic cables safely decouple the units in accordance with DIN VDE 0100 and DIN VDE 0160 (PELV function, e.g. for NAMUR).

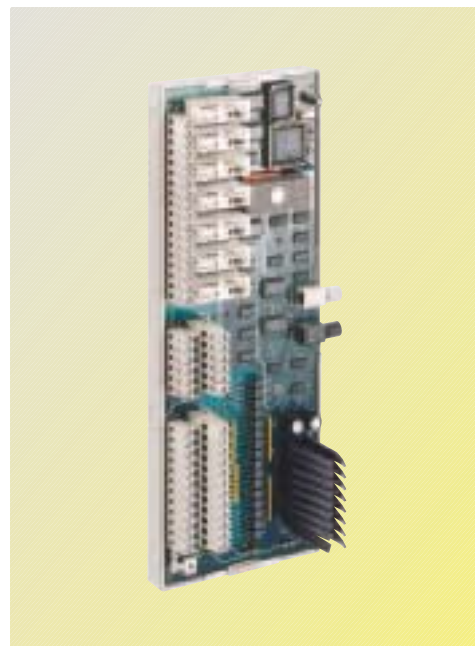
The fiber-optic cables, which can have a maximum length of 10 m (33 ft) and a minimum length of 0.3 m (1 ft), connect the boards in a ring structure. Both the SCI1 and the SCI2 require an external 24 V power supply (1 A each).

All the inputs and outputs of the interface boards can be parameterized.

The SCI1 and SCI2 interface boards can be snapped onto a DIN rail at a suitable place in the control cabinet.



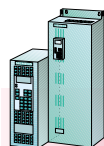
SCI1 interface board



SCI2 interface board

Inputs and outputs Functions	SCI1	SCI2	Description
Binary inputs	10	16	Floating optocoupler inputs in 2 circuits 24 V DC, 10 mA
Binary outputs including:	8	12	Load capability
Relay changeover contacts	4	4	250 V AC, 2000 VA ($\cos \varphi = 1$)
Relay make contacts	3	3	100 V DC, 240 W
Transistor outputs	1	5	240 V DC, max. 100 mA, short-circuit-proof, open-emitter for driving the optocouplers or relays
Analog inputs	3	–	Voltage signals: 0 to ± 10 V Current signals: 0 to ± 20 mA; 4 mA to 20 mA, 250 Ω burden Non-floating inputs
Analog outputs	3	–	Output signals 0 V to ± 10 V, 0 mA to ± 20 mA, 4 mA to 20 mA, non-floating Max. cable length with shielded cables is 100 m (33 ft) Max. load 500 Ω
Supply voltage:			
Reference voltage			
+10 V	1	–	5 mA load capability, short-circuit-proof
–10 V	1	–	5 mA load capability, short-circuit-proof
24 V DC	2	2	Short-circuit-proof output for binary inputs or outputs, load capability 280 mA

Technical data	
Mounting	DIN mounting rail (see Section 3)
Rated external input voltage	24 V DC (–17 %, +25 %), 1 A
Degree of protection	IP00
Dimensions H x W x D	SCI1: 95 mm x 300 mm x 80 mm (3.7 in x 11.8 in x 3.15 in) SCI2: 95 mm x 250 mm x 80 mm (3.7 in x 9.8 in x 3.15 in)



Compact and
chassis units



Compact
PLUS units

SIMOVERT MASTERDRIVES Motion Control

Engineering information

Electronics options

Control terminal strip on the SCI1 interface board for cabinet units with PMU or OP1S and the option "NAMUR terminal strip"

Terminal	No.	Type	Preassignment	Notes
X427	A1	P24		
	A2	M		
	A3	BE6	Setpoint lower	
	A4	BE7	Acknowledge	
	A5	BE8	Off 2	
	A6	BE9	Select counter-clockwise rotating field	
	A7	BE10	None	
	A8	M		
	A9	M		
	A10	M		
	A11	M		
X427	B1	P24		
	B2	BA8	None	Transistor output
	B3	BE1	On/Off 1	
	B4	BE2	Select BICO data set 2	Local/remote operation
	B5	BE3	None	
	B6	BE4	None	
	B7	BE5	Setpoint higher	
	B8	M		
	B9	P24		
	B10	P24		
	B11	P24		
X428	1	+10 V stab		
	2	-10 V stab		
	3	AE1 ±10 V	Main setpoint	Analog input 1
	4	M		
	5	AE1 ±20 mA		Load 250 Ω
	6	AE2 ±10 V	None	Analog input 2
	7	M		
	8	AE2 ±20 mA		Load 250 Ω
	9	AE3 ±10 V	None	Analog input 3
	10	M		
	11	AE3 ±20 mA		Load 250 Ω
	12	AA1 ±10 V	Speed	Analog output 1
	13	M		
	14	AA1 ±20 mA		Load, max. 500 Ω
	15	AA2 ±10 V	Output current	Analog output 2
	16	M		
	17	AA2 ±20 mA		Load, max. 500 Ω
	18	AA3 ±10 V	Torque	Analog output 3
	19	M		
	20	AA3 ±20 mA		Load, max. 500 Ω
X429	1	BA1	Ready for power-on	Relay contact
	2			
	3	BA2	Setpoint reached	Relay contact
	4			
	5	BA3	Off 2 signal	Relay contact
	6			
	7	BA4	Fault	Changeover contact: common
	8			break contact NC
	9			make contact NO
	10	BA5	None	Changeover contact: common
	11			break contact NC
	12			make contact NO
	13	BA6	None	Changeover contact: common
	14			break contact NC
	15			make contact NO
	16	BA7	None	Changeover contact: common
	17			break contact NC
	18			make contact NO

Relay contacts, maximum loading 100 V DC, 2.4 A or with 250 V AC, 8 A.